

Optimal Taxation in a Life-Cycle Economy with Endogenous Human Capital Formation: A Review

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Introduction

- **This presentation:** Overview of selected results on dynamic optimal taxation in an environment where
 - Human capital is endogenous
 - Individual's abilities are unobservable and permanent
- I will cover several cases:
 - Human capital is observable and deterministic
 - Human capital is unobservable and deterministic
 - Human capital is observable and has unobservable stochastic returns
 - Human capital is unobservable and has unobservable stochastic returns
- I will focus on the case when the cost of accumulating human capital is time, not physical resources
- This presentation will focus on qualitative results. However, one goal of this research is to allow for quantitative characterization of the optimal tax policies

0. Static Optimal Taxation

- A standard static optimal taxation model (Mirrlees 1971):
 - Question: How should a government design a tax system that maximizes some utilitarian social welfare function?
 - Individuals have abilities $\theta \in \Theta$
 - Abilities are private information: The government only knows their distribution $Q(\cdot)$
 - People choose labor supply l and consumption c . Income is $y = w l$.
 - c and y is observable, l and θ is not.
 - Taxation principle: Anything that can be achieved by an income tax function can be achieved in a direct revelation mechanism with incentive constraints

0. Static Optimal Taxation

- The planner's problem:

- Maximize some social welfare function by choosing $\{c(\theta); y(\theta)\}$
- subject to an incentive constraint

$$U(c(\theta)) - V\left(\frac{y(\theta)}{\theta}\right) \geq U(c(\hat{\theta})) - V\left(\frac{y(\hat{\theta})}{\hat{\theta}}\right);$$

- and a resource constraint

$$\int [c(\theta) - l(\theta)] dQ(\theta) \leq 0;$$

- Replace the incentive constraint by an envelope condition:

$$U(c(\theta)) - V(l(\theta)) = w_0 + \int_{\underline{\theta}}^{\theta} V_l(l(\theta')) l(\theta') \frac{d\theta'}{\theta'};$$

0. Static Optimal Taxation

- Diamond (1998) shows that with $U(c) = c$ the optimal intratemporal wedge $\tau(\cdot) = 1 - \frac{V'(l)}{\theta}$ satisfies

$$\frac{\tau(\cdot)}{1 - \tau(\cdot)} = (1 + \eta^{-1})X(\cdot)$$

where η is the elasticity of labor supply, $X(\cdot)$ is given by

$$X(\cdot) = \frac{1 - Q(\cdot)}{q(\cdot)} C(\cdot)$$

and $C(\cdot)$ depends on the social welfare function.

- For instance, if the planner is Rawlsian then $C(\cdot) = 1$.
- If the shock support is finite, $X(\bar{\cdot}) = 0$ (no distortion at the top)

1. Deterministic Human Capital

- Agents live for $J > 1$ periods. They consume, work, and learn.
- Preferences:

$$\sum_{j=1}^J \beta^{j-1} [U(c_j) - V(l_j; s_j)]; \quad 0 < \beta < 1; \quad (1)$$

- Labor Earnings:

$$y_j = w_j l_j \quad (2)$$

- Human capital formation:

$$h_{j+1} = F(h_j; s_j) \quad (3)$$

- c is consumption, l is labor, s is schooling effort, h is beginning of period human capital.
- c and y are always observable. h is always unobservable.

1.1. Deterministic and Observable Human Capital

- Allocation: $(c; y; h) = \{c_j(\cdot); y_j(\cdot); h_{j+1}(\cdot)\}_{j=1}^J$

- Lifetime utility:

$$W_{y,c,h}(\hat{\cdot} | \cdot; h_1) = \sum_{j=1}^J \beta^{j-1} \left[U(c_j(\hat{\cdot})) - V \left(\frac{y_j(\hat{\cdot})}{h_j(\hat{\cdot})}; S(h_j(\hat{\cdot}); h_{j+1}(\hat{\cdot})) \right) \right]$$

- Incentive compatibility:

$$W_{y,c,h}(\cdot | \cdot; h_1) \geq W_{y,c,h}(\hat{\cdot} | \cdot; h_1) \quad \forall \hat{\cdot} \in \Theta: \quad (4)$$

- Resource constraint

1.1. Deterministic and Observable Human Capital

- Replace the incentive constraint by an envelope condition:

$$W_{y,c,h}(\cdot | \cdot; h_1) = \int_{\underline{\theta}}^{\theta} \sum_{j=0}^J t^{-1} V_{l,j}(\cdot) l_j(\cdot) \frac{d''}{''} + W_{y,c,h}(\cdot | \cdot; h_1); \quad (5)$$

where $V_{l,j}(\cdot) = V_l(l_j(\cdot); s_j(\cdot))$

- Characterize the optimum by the following:
 - The *intra-temporal wedge*

$$\Delta_j \equiv 1 - \frac{V_l(l_j; s_j)}{h_j U_c(c_j)}$$

- The *human capital wedge*

$$\Delta_j \equiv \frac{V_{s,j}}{F_{s,j}} - \left(V_{l,j+1} \frac{l_{j+1}}{h_{j+1}} + V_{s,j+1} \frac{F_{h,j+1}}{F_{s,j+1}} \right) \quad (6)$$

1.1. Deterministic and Observable Human Capital

Example 1

Assumption (Example 1)

$$V(l; s) = \frac{l^{1+\nu^{-1}}}{1+\nu^{-1}} + \frac{s^{1+\epsilon^{-1}}}{1+\epsilon^{-1}}, \quad U(c) = c \text{ and } F(h; s) = s.$$

- The intratemporal wedge

$$\frac{l_j(\cdot)}{1 - l_j(\cdot)} = (1 + \tau_j) X(\cdot) \quad (7)$$

- The intertemporal wedge

$$\Delta_j(\cdot) = (1 + \tau_j) X(\cdot) \frac{l_{j+1}(\cdot)^{1+\nu^{-1}}}{s_j(\cdot)} \geq 0:$$

- Main implications:

- Intratemporal wedge is the same as in the static model
- Schooling subsidies provided to encourage investment in human capital

1.1. Deterministic and Observable Human Capital

Example 1

- Separable utility drives the constant intratemporal wedge
- Human capital wedge corrects for the fact that private benefits from investment in human capital are smaller than social benefits from investment in human capital
- DaCosta and Maestri (2007) show that the result is modified if human capital can help to separate people of different skills

1.1. Deterministic and Observable Human Capital

Example 2

Assumption (Example 2)

$$V(l; s) = \frac{(l+s)^{1+\nu^{-1}}}{1+\nu^{-1}}, \quad U(c) = c \quad \text{and} \quad F(h; s) = s.$$

- The intratemporal wedge

$$\frac{j(\cdot)}{1 - j(\cdot)} = (1 + [(1 + \frac{s_j(\cdot)}{l_j(\cdot)})^{-1}]X(\cdot)) \quad (8)$$

- The elasticity term is now endogenous
- Higher schooling to labor ratio decreases the intratemporal wedge
 - Makes the tax system initially more regressive relative to a static economy
 - Intratemporal wedge should be increasing over the life-cycle

1.2. Deterministic and Unobservable Human Capital

- The incentive compatibility constraint:

$$h = \arg \max_{\hat{h}} W_{c,y,\hat{h}}(\cdot | \cdot ; h_1) \quad (9)$$

$$W_{c,y,h}(\cdot | \cdot ; h_1) \geq \max_{\hat{h}} W_{c,y,\hat{h}}(\cdot | \cdot ; h_1) \quad \forall \hat{h} \in \Theta: \quad (10)$$

- Necessary conditions for incentive compatibility:
 - Envelope condition (the same as before)
 - Euler equation in HC investment:

$$\frac{V_{s,j}}{F_{s,j}} = \left(V_{l,j+1} \frac{l_{j+1}}{h_{j+1}} + V_{s,j+1} \frac{F_{h,j+1}}{F_{s,j+1}} \right) \quad (11)$$

- Incentives to accumulate human capital must now be provided differently

1.2. Deterministic and Unobservable Human Capital

Example 1 cont'd

Assumption (Example 1)

$$V(l; s) = \frac{l^{1+\nu^{-1}}}{1+\nu^{-1}} + \frac{s^{1+\epsilon^{-1}}}{1+\epsilon^{-1}}, \quad U(c) = c \quad \text{and} \quad F(h; s) = s.$$

- The intratemporal wedge is given by

$$\frac{1(\cdot)}{1 - 1(\cdot)} = (1 + \hat{\tau}^{-1})X(\cdot)$$

$$\frac{j(\cdot)}{1 - j(\cdot)} = (1 + \hat{\tau}^{-1})X(\cdot); \quad j = 2 \dots J;$$

where $\hat{\tau} = \frac{2+\nu^{-1}+\epsilon^{-1}}{\nu^{-1}\epsilon^{-1}-1} > \cdot$.

- Lower wedge for $j \geq 2$: labor supply is complementary with previous human capital investment

1.2. Deterministic and Unobservable Human Capital

Example 2 cont'd

Assumption (Example 2)

$$V(l; s) = \frac{(l+s)^{1+\nu-1}}{1+\nu-1}, \quad U(c) = c \quad \text{and} \quad F(h; s) = s.$$

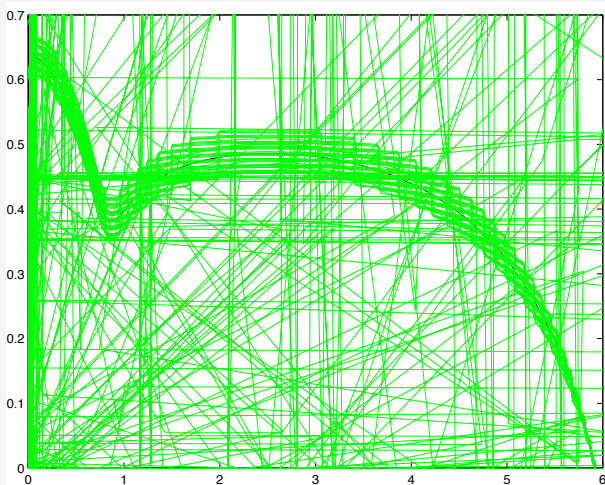
- For $J = 3$ one can show that the intratemporal wedge satisfies

$$\tau_1(\cdot) > \tau_2(\cdot) > \tau_3(\cdot) > 0:$$

- Complementarity of current schooling with future labor and substitutability of current schooling with current labor imply decreasing wedge
- Changes in labor elasticity imply increasing wedge
- The first effect dominates

Bohacek/Kapicka (2007): A calibrated infinite horizon economy

$$h' = (1 - \alpha)h + (hs)^\alpha$$



2. Stochastic Human Capital

- Human capital accumulation

$$h_{j+1} = e^{z_{j+1}}(h_j + (h_j s_j)^\alpha); \quad z_j \sim i.i.d.$$

- z and s are both private information
- Private information from unobservability of individual abilities and labor
- Moral hazard problem from unobservable schooling effort and rates of return
- Can be mapped into Huggett, Ventura, Yaron (AER, 2011)

2.1. Stochastic and Observable Human Capital

- Social planner chooses $(c; y; s) = \{c_j(\cdot; h^j); y_j(\cdot; h^j); s_j(\cdot; h^j)\}$
- Lifetime utility

$$\begin{aligned}
 & W_{c,y,s}(\hat{\cdot} \mid ; h_1) \\
 &= \sum_{j=1}^J \beta^{j-1} \int_{H^{j-1}} \left[U(c_j(\hat{\cdot}; h^j)) - V\left(\frac{y_j(\hat{\cdot}; h^j)}{ah_j}; s_j(h^j)\right) \right] P^j(h^j \mid h_1; s^{j-1}(h^{j-1})) dh^j
 \end{aligned}$$

- Incentive compatibility

$$s = \arg \max_{\hat{s}} W_{c,y,\hat{s}}(\hat{\cdot} \mid ; h_1) \quad (12)$$

$$W_{c,y,s}(\hat{\cdot} \mid ; h_1) \geq \max_{\hat{s}} W_{c,y,\hat{s}}(\hat{\cdot} \mid ; h_1) \quad \forall \hat{\cdot}; \hat{\cdot} \in \Theta \forall h_1 \in H \quad (13)$$

2.1. Stochastic and Observable Human Capital

Relaxed Planning Problem in a 2 period version

Assume 2 periods, expected utility maximization, and let $W(\cdot) = W_{c,y,s}(\cdot | \cdot; h_1)$

$$\max \int W(\cdot) q(\cdot) d$$

subject to

$$\int_{\theta} \left[c_1(\cdot) - y_1(\cdot) + R^{-1} \int_H [c_2(\cdot; h_2) - y_2(\cdot; h_2)] P(h_2|s_1) dh_2 \right] q(\cdot) d \leq 0:$$

$$V_s \left(\frac{y_1(\cdot)}{h_1}; s_1 \right) = \int_{\underline{h}}^{\bar{h}} \left[U(c_2(\cdot; h_2)) - V \left(\frac{y_2(\cdot; h_2)}{h_2}; 0 \right) \right] P_s(h_2|s_1) dh_2$$

$$W(\cdot) = W(\cdot) + \int_{\underline{\theta}}^{\bar{\theta}} \left[V_{\ell} \left(\frac{y_1(\cdot)}{h_1}; s_1(\cdot) \right) \frac{y_1(\cdot)}{h_1} + \int_{\underline{h}}^{\bar{h}} V_{\ell} \left(\frac{y_2(\cdot; h_2)}{h_2}; 0 \right) \frac{y_2(\cdot; h_2)}{h_2} P(h_2|s_1(\cdot)) dh_2 \right] \frac{d\cdot}{\cdot}$$

2.1. Stochastic and Observable Human Capital

Inverse Euler Equation

Proposition

$$\frac{1}{U'(c_1(s_1))} = \int_H \frac{1}{U'(c_2(s_1; h_2))} P(h_2 | s_1) dh_2$$

by Jensen's Inequality,

$$U'(c_1(s_1)) < \int_H U'(c_2(s_1; h_2)) P(h_2 | s_1) dh_2$$

2.1. Stochastic Observable Human Capital

Example 1 cont'd

Proposition

Suppose that $V(l; s) = \frac{l^{1+\nu^{-1}}}{1+\nu^{-1}} + \frac{s^{1+\epsilon^{-1}}}{1+\epsilon^{-1}}$. Then

$$\frac{1}{1(\cdot)} = \int_H \frac{1}{2(\cdot; h_2)} P(h_2 | s_1(\cdot)) dh_2:$$

by Jensen's Inequality,

$$1(\cdot) < \int_H 2(\cdot; h_2) P(h_2 | s_1(\cdot)) dh_2$$

Intratemporal wedge increases over time!

Intratemporal Wedges

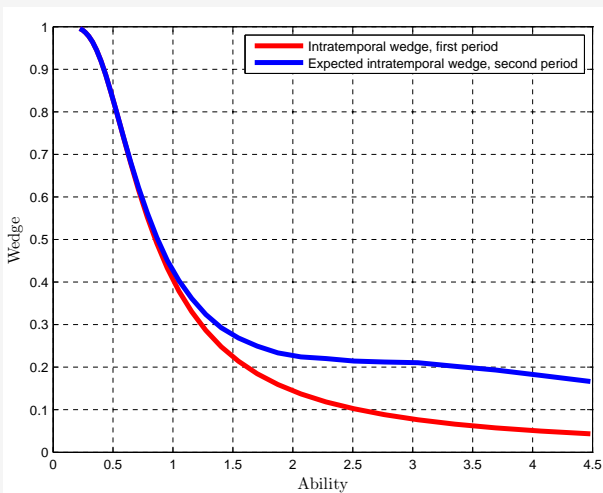


Figure: Intratemporal Wedges

Intratemporal Wedge Second Period

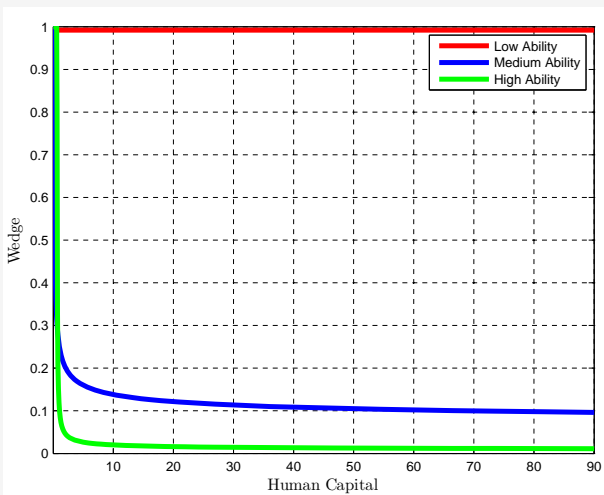


Figure: Intratemporal Wedge in the Second Period

2.2. Stochastic Unobservable Human Capital

- The most complicated: large number of deviations
- Grochulski and Piskorski (2007): solution for a special case:
 - investment in human capital only in the initial period
 - no labor supply in the initial period
 - depreciation shocks take only two values $e^z \in \{0; 1\}$
 - the low shock is absorbing

2.2. Stochastic Unobservable Human Capital

- Two novel results:
 - No distortion at the top does not apply: negative intratemporal wedge at the top
 - Stronger front-loading of consumption
- Both features relax the incentive constraints
- Not obvious if the first result survives in an economy with e.g. continuum of shocks
- The second result is similar to the higher tax in the initial period

3. Conclusions

- Main results:
- Corrective schooling subsidies whenever schooling effort is observable
- If not possible, use intertemporal variations in taxes to provide incentives to accumulate human capital
- The exact pattern depends on
 - substitutability/complementarity of human capital and schooling
 - changes in labor supply elasticity
 - riskiness of human capital investments
- More generally, one of the important questions is if human capital investments are useful in separating people of different skills